

AV Demand Simulation

Autonomous Vehicles and Behavioral Modeling

June 27, 2018

Background

- UC Berkeley: Civil/Environmental Engineering (Transportation Systems), 2018



President (2017-2018)

- Research Assistant at the Institute of Transportation Studies

Project Background

- Modeling the demand of various automated vehicles
- Trying to nudge travelers into shared mobility
 - Environmental, time, socioeconomic benefits
- Pricing vs. Lane Allocation

Heaven

- All electric
- Shared Fleet
(subscription or pay
as you go)
- Shared Rides
- Technology will solve
many current
transportation
problems



Hell

- Maybe electric and efficient
- Not shared
- Behavioral change → Huge increases in VMT (as much as 70% potentially)
- Curb access stressed
- Streets are safe but not desirable



Will AVs really solve this?

CPF
cycling promotion fund



Set Up

- 10 mile freeway stretch, 5 lanes
- 3 modes of transportation:
 - Private AV (Personal Auto)
 - Shared AV (Uber/Lyft)
 - Shared Ride AV (Uber Pool/Lyft Line)
- 3 cases to study:
 - Base (all mixed flow, no pricing)
 - Pricing
 - Lane allocation



Simulation

- Simulate the demand for each mode of transportation using a Logit Model
- Simulate travel time using Bureau of Public Roads (BPR) formula
- All other inputs are derived from previous studies/estimated by us

Logit Model

- Calculate the utility of each mode using a variety of inputs

$$V_{SAV} = ASC_{SAV} + \beta_{cost} \times Cost_{SAV} + \beta_{TT} \times TT_{SAV}$$

- Use Logit Equation to predict probability

$$\text{Pr}(i) = \frac{\text{utility of mode } i}{\sum_{j=1}^J \text{utility of mode } j}$$

probability of mode i

utility of mode i

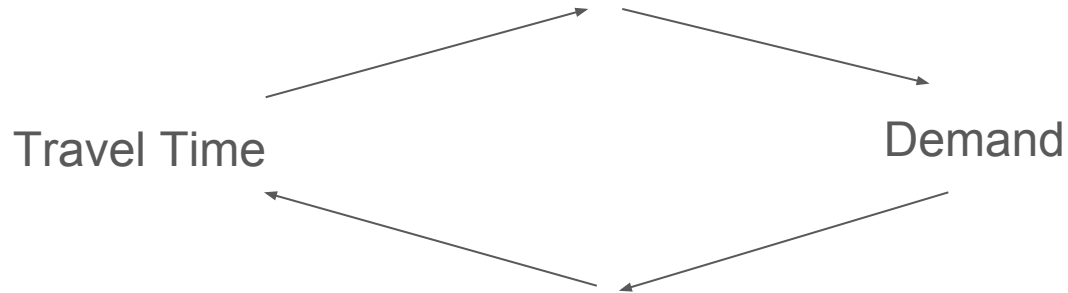
sum of J modes utility of ($j=1,2,3\dots J$) mode j

BPR Formula for travel time

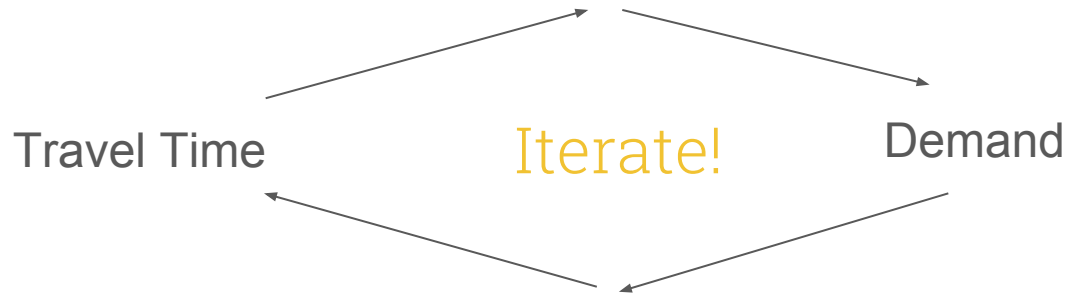
- Use ratio of demand/capacity to calculate the travel time

$$TT = FF \times (1 + \alpha c^\beta)$$

Dependency



Iterate



Iteration Process

1. Ignoring travel time, calculate initial demand estimates

Iteration Process

1. Ignoring travel time, calculate initial demand estimates
2. Then calculate travel times

Iteration Process

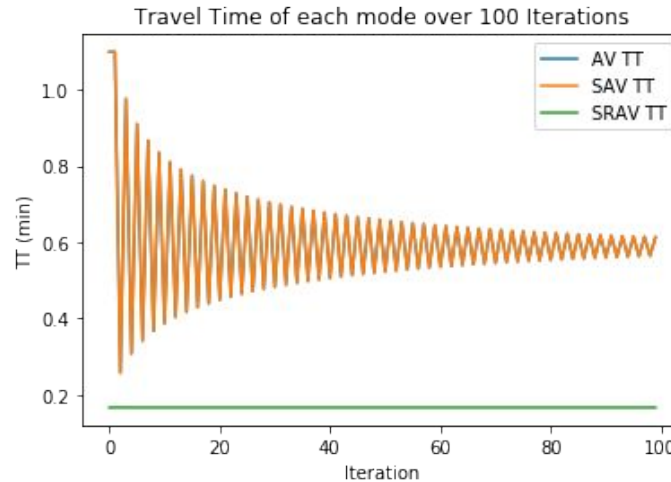
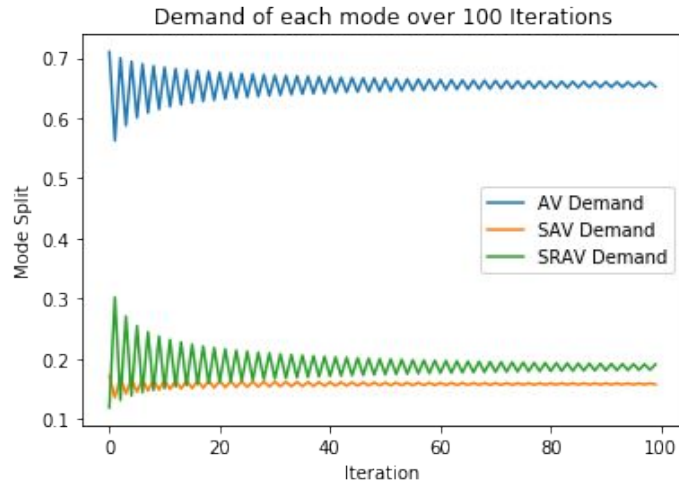
1. Ignoring travel time, calculate initial demand estimates
2. Then calculate travel times
3. Calculate new demands

Iteration Process

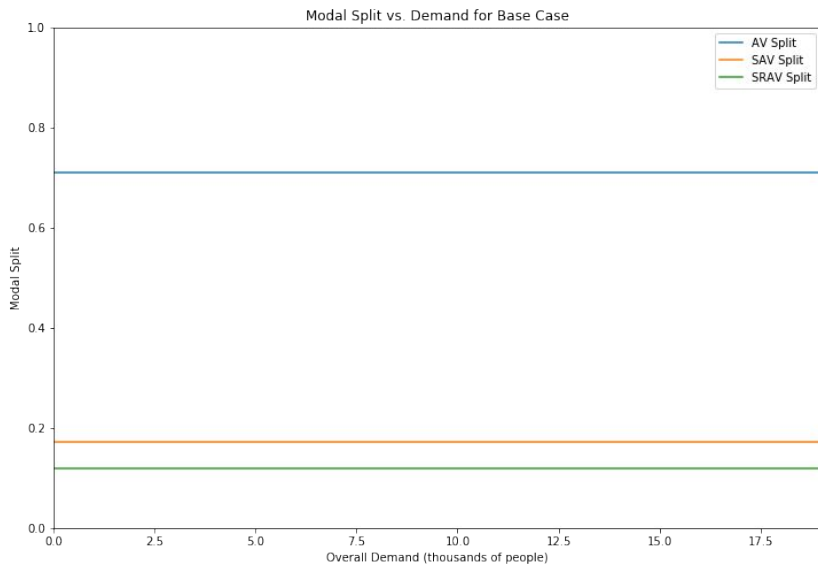
1. Ignoring travel time, calculate initial demand estimates
2. Then calculate travel times
3. Calculate new demands
4. Repeat 2 & 3 until convergence

Iteration Process

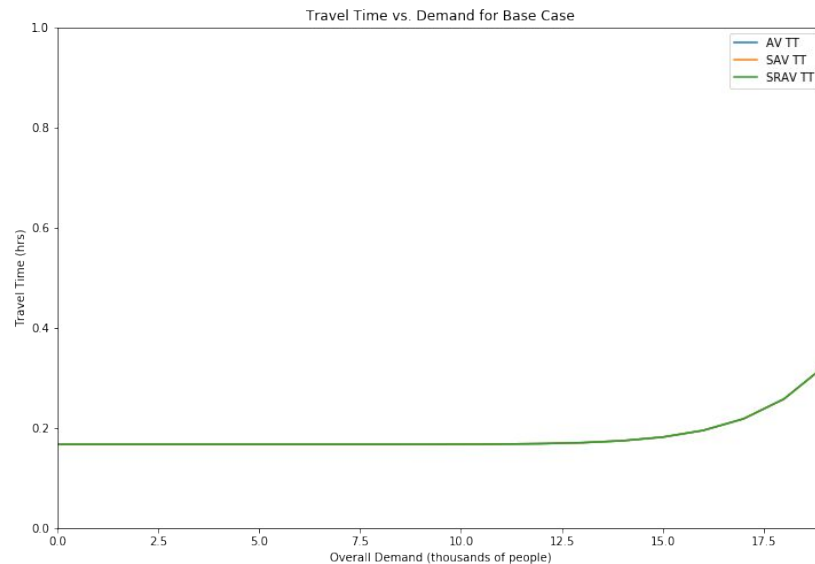
1. Ignoring travel time, calculate initial demand estimates
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Results: Base Case

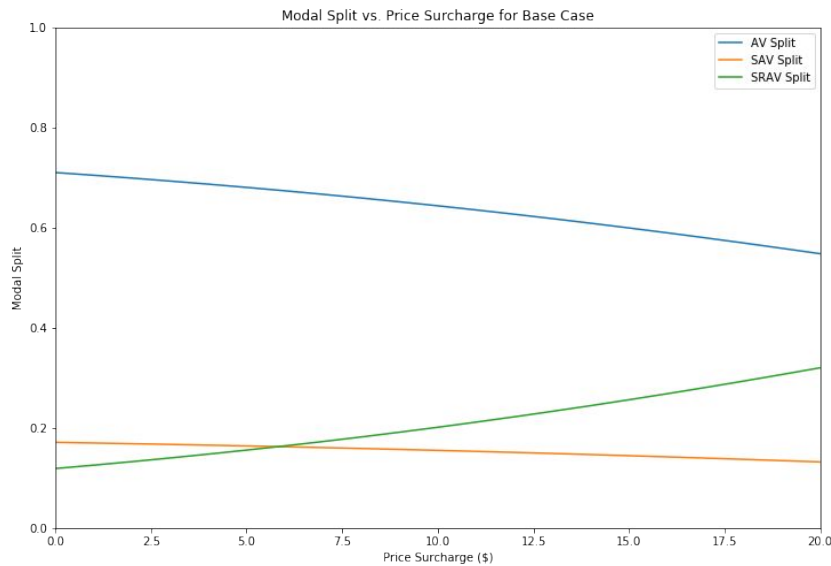


Mode shares are constant, demand is irrelevant

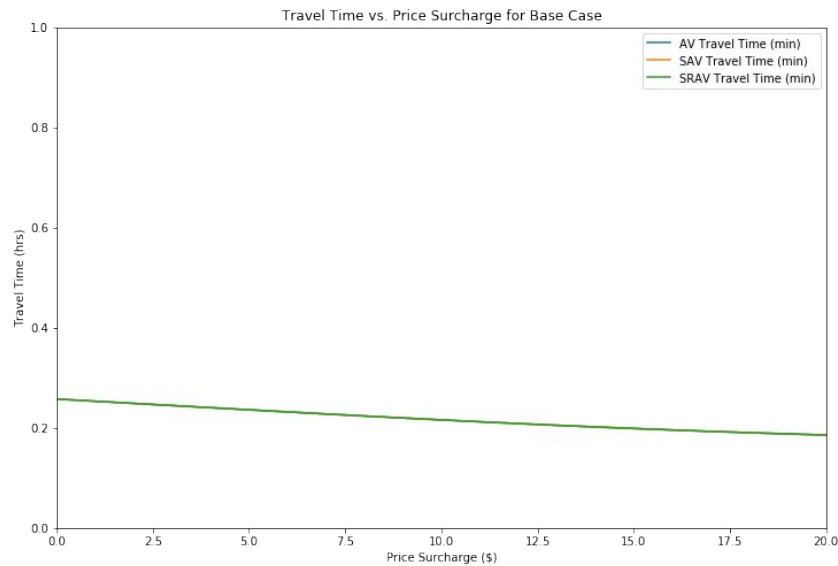


Uniform travel time, starts to increase as system is stressed

Results: Price Surcharge

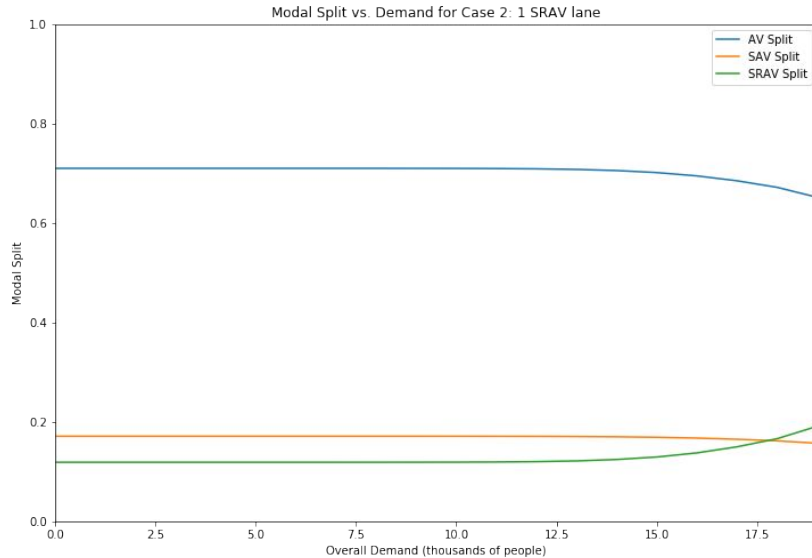


Shared increases with price surcharge, others decrease

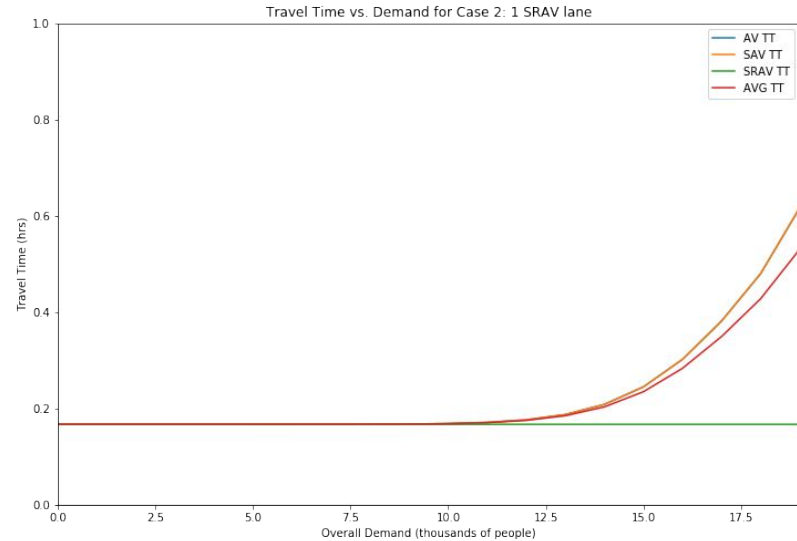


Overall travel time savings for all modes

Results: Lane Allocation



Low Demand: no difference from base
High Demand: mode shift to shared



As demand increases, low
occupancy travel time increases

Limitations & Areas for Improvement

- Any number of lane allocation and pricing schemes could be modeled
- Greater accuracy in input parameters is needed
- Induced demand
- Want to model even higher stress points for longer travel times

Conclusions

71% (AV), 17% (SAV), 12% (AV) → 65% (AV), 16% (SAV) and 19% (SRAV)

Equivalence point between high occupancy lane and pricing appears to be a \$9/person fee, for the given conditions

Pricing will work at low demand, lane works when system approaches capacity

Lane allocation will penalize low occupancy with travel delays, surcharge produces travel time savings for all

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